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# Shadow Considerations

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# Shadows

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- **One of the most important graphical parts of game engine**
- **Influence on several aspects of game**
  - **Artwork creation and pipeline**
  - **Min spec, fallbacks**
  - **Shader complexity**
  - **Batch size**
  - **Performance**

# Strategic Considerations

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- **What objects cast shadows?**
- **What objects receive shadows?**
- **How do shadows integrate with the art pipeline?**
- **What technique for shadows**
  - **One technique or multiple?**
- **Static lighting v. Dynamic lighting**



# Tactical Considerations

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- **Light Maps, Precomputed Radiance Transfer, Blobs, ...**
- **Shadow Volumes or Shadow Maps?**
  - **Both?**
- **Issues arising from usage of either**
  - **World Geometry v. Local Geometry**
  - **Aliasing problems**
  - **CPU side computations v. GPU computations**
  - **...**



# Two Broad Approaches

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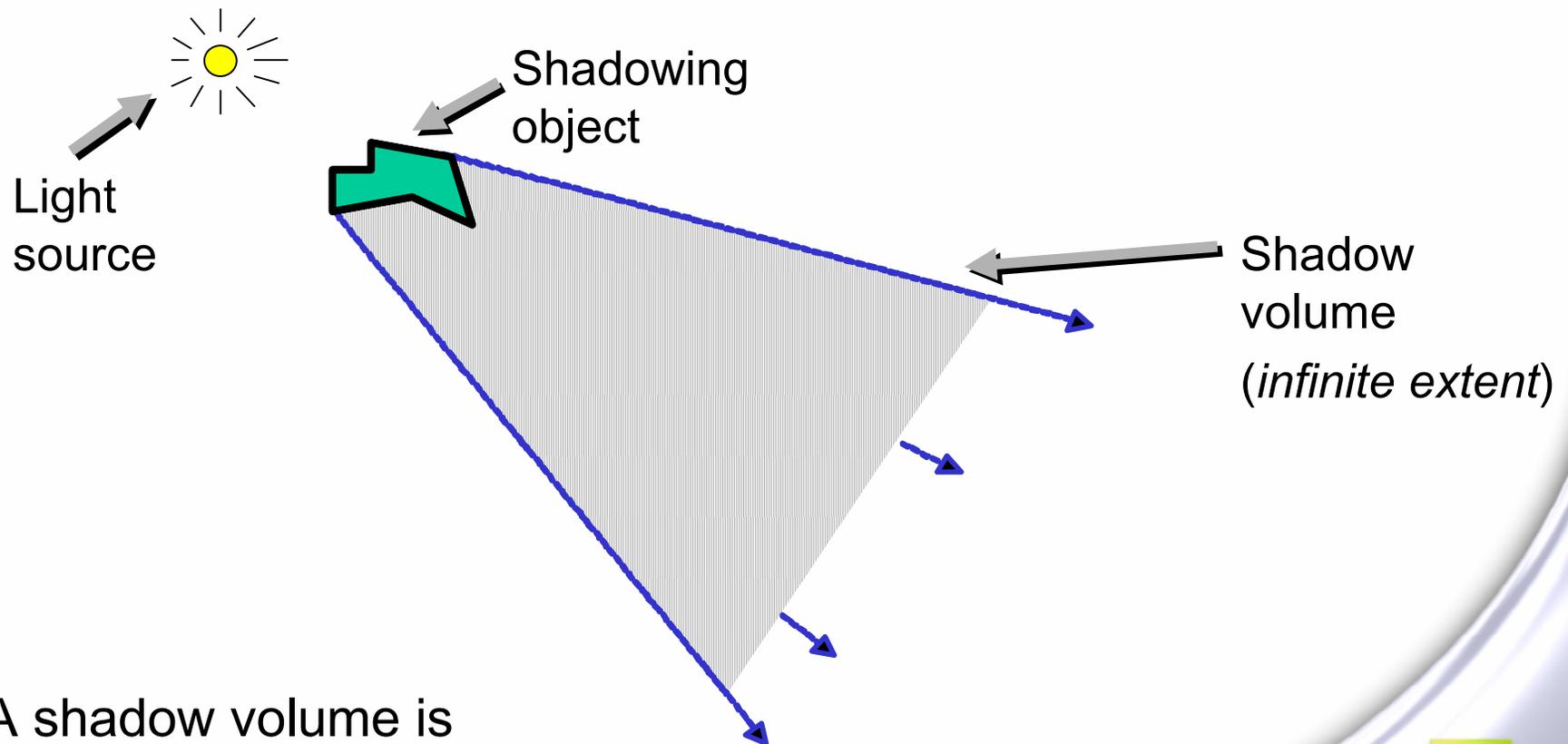
- ***Shadow Volumes and Shadow Maps***
- **No one 'right' technique**
- **Shadow volumes**
  - **Mathematically elegant, 'complete', omni-directional**
- **Long term, however, we expect shadow maps to be more widely used**
  - **Better scaling with GPU power**
  - **Softer edges**
  - **Applicable to different kinds of geometry**
    - **No alpha test issues**



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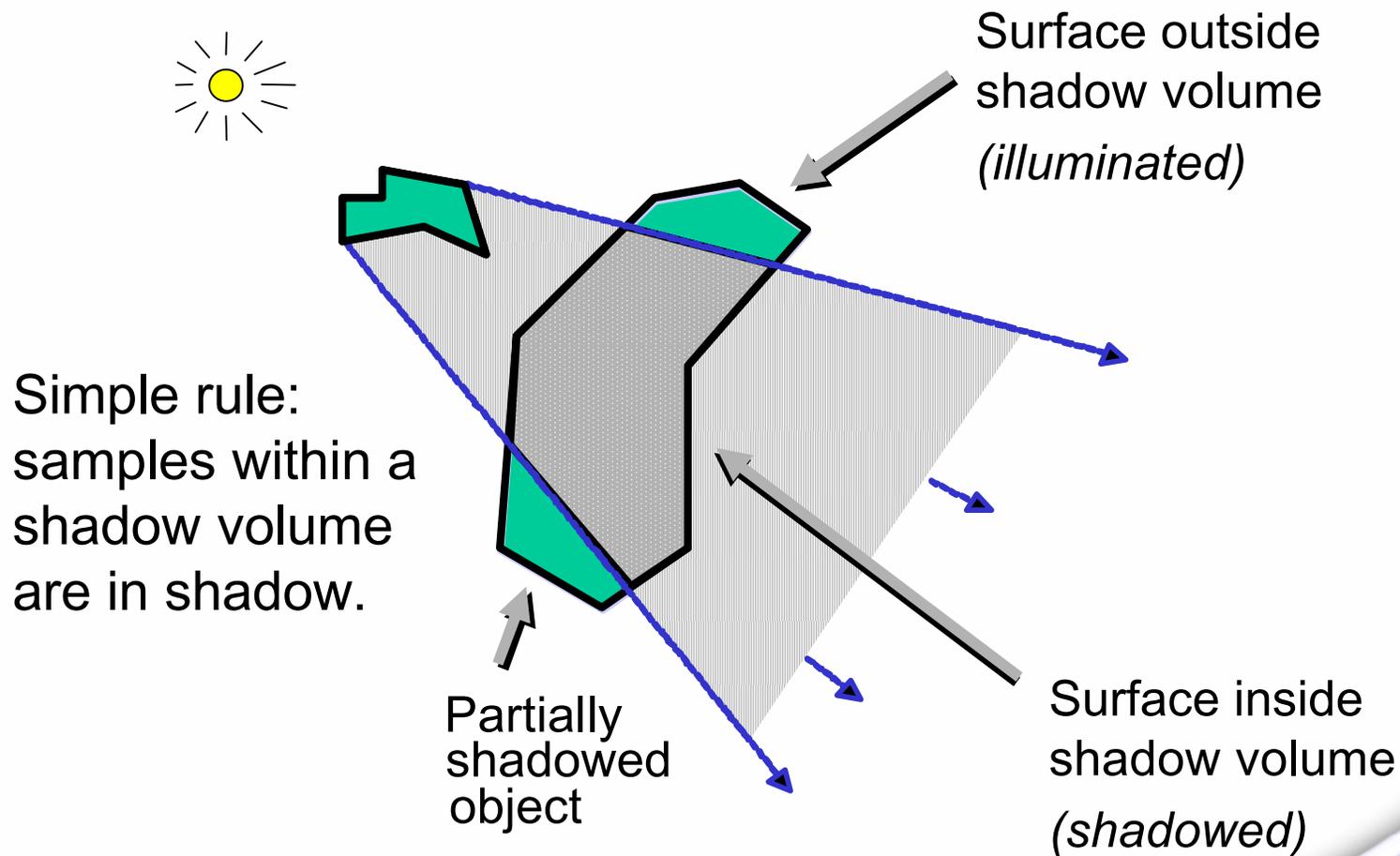
# Shadow Volumes – Basic Concept



A shadow volume is simply the half-space defined by a light source and a shadowing object.

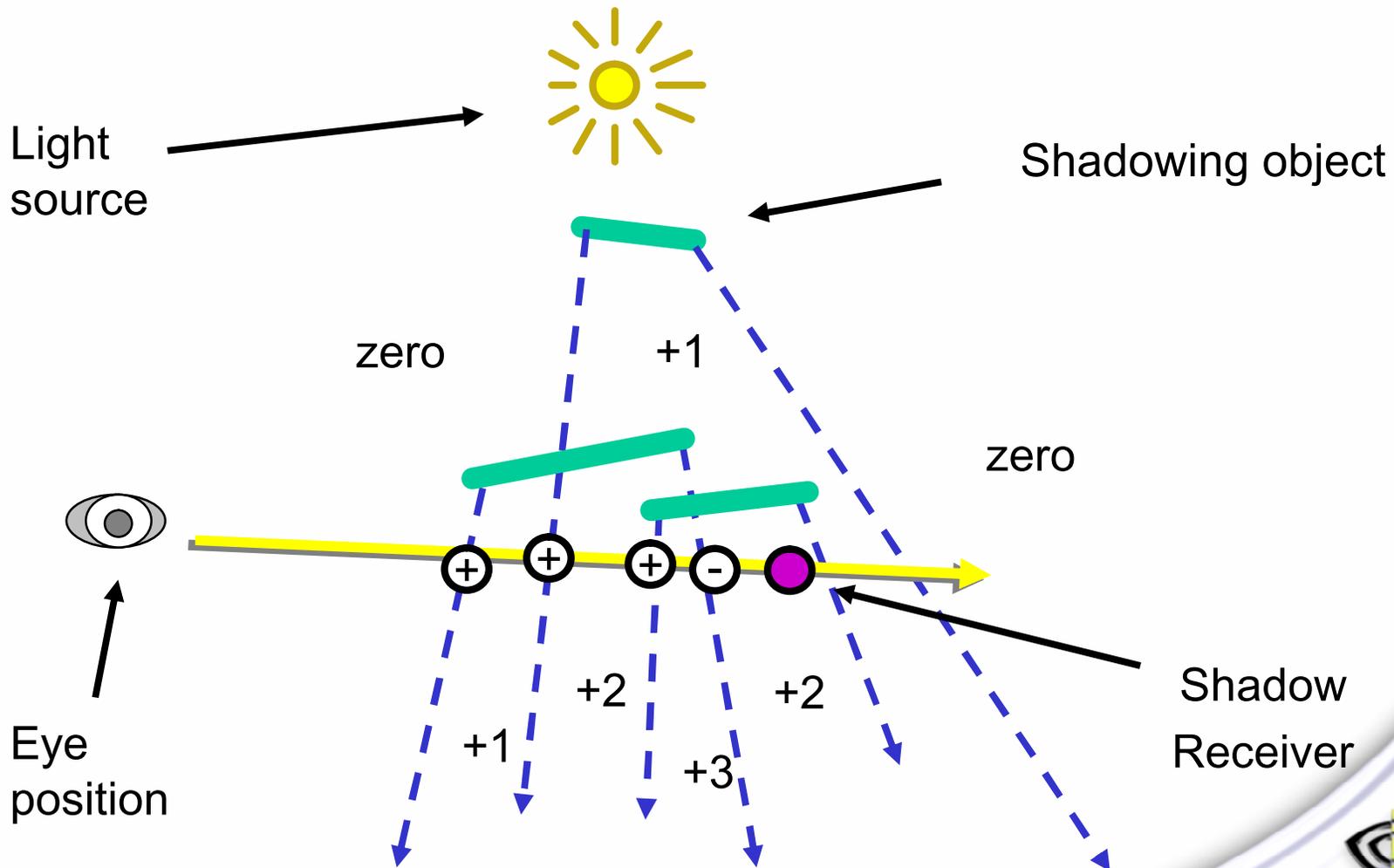


## Shadow Volumes – Basic Concept (2)





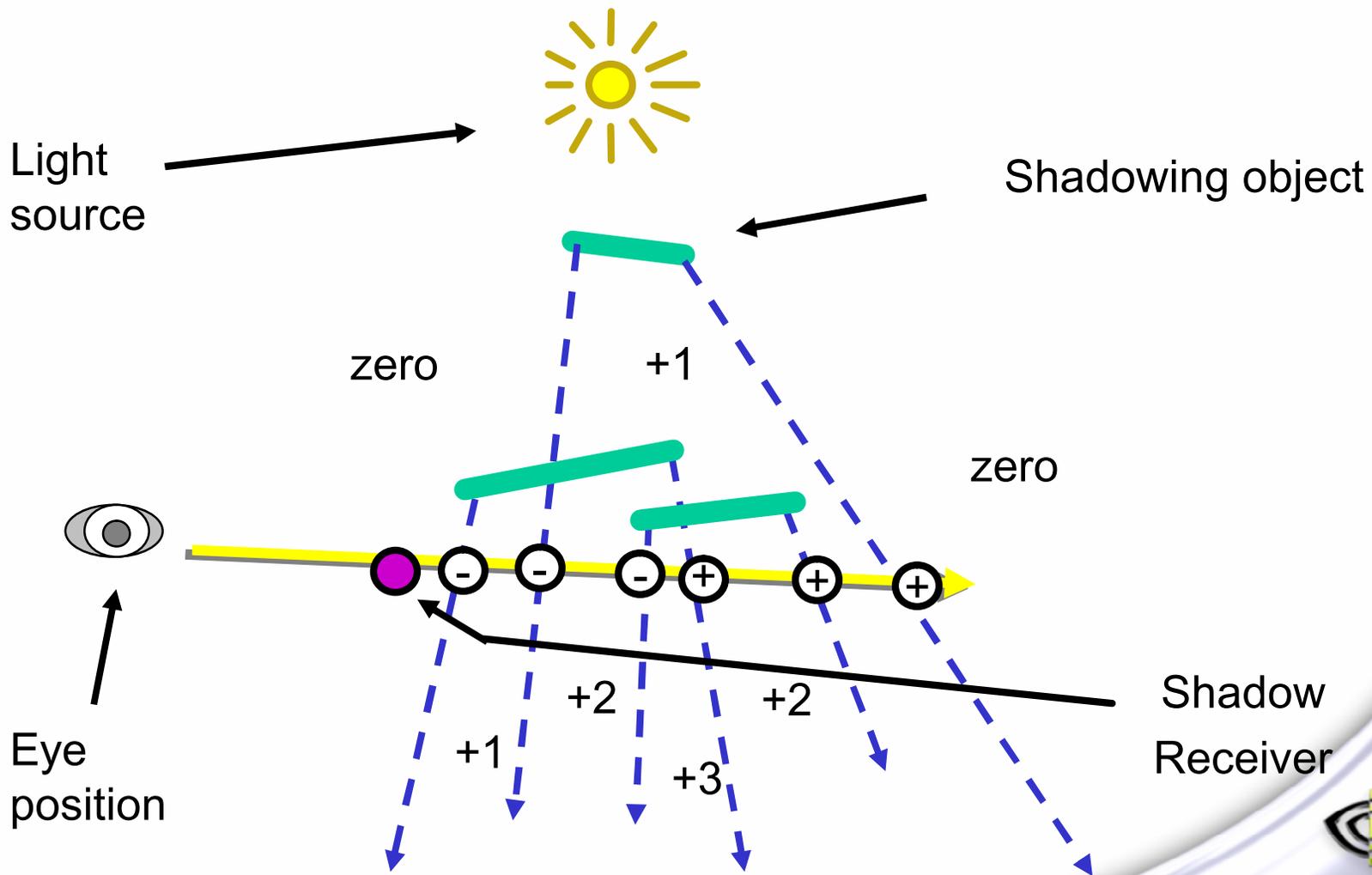
# Stencil Shadow Volumes (zpass)



$$\text{Shadow Volume Count} = +1 + 1 + 1 - 1 = 2$$



# Stencil Shadow Volumes (zfail)



**Shadow Volume Count =  $-1-1-1+1+1+1 = 0$**



# Shadow Volumes – Silhouettes

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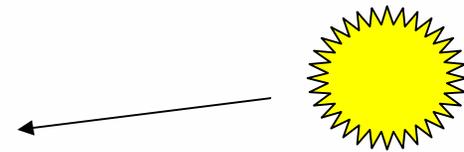
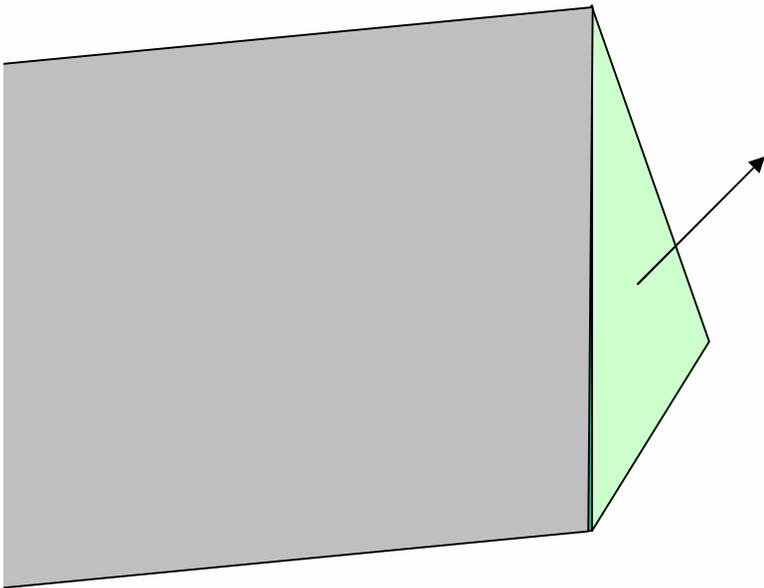
- How to compute volumes?
- Compute (projected 2D) silhouettes instead and extrude
- One big question to answer when using shadow volumes is how to determine silhouettes
  - On CPU, performing edge tests
  - On GPU, using degenerate geometry on each edge



# Silhouette Computation on the CPU

- **Requires faces to know neighboring faces**
  - **For each face**
    - Calculate dot product of face normal with light vector
  - **For each face**
    - Check 3 neighboring faces' dot products
    - If dot product of face a is  $\leq 0.0$ , and face b is  $> 0.0$ 
      - Then the edge between a & b is a silhouette edge
    - Construct quad along edge by extruding away from light

# CPU Silhouettes – Quad Extrusion





# Pros and Cons of CPU Silhouettes

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- **+ Straightforward algorithm**
- **+ Linear in the number of faces**
- **+ Only need to recompute when light or objects move (relative to each other)**
- **+ Works well with skinning**
  - **Skin on CPU, then compute silhouette**
- **- Can be expensive for dense meshes**



# Shadow Volumes on the GPU

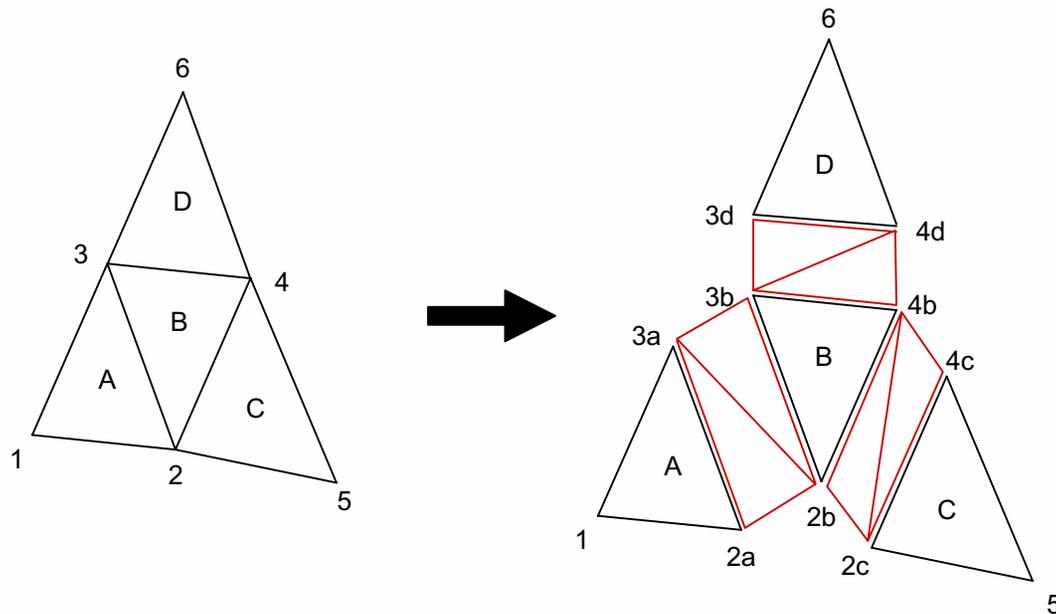
- Insert 'degenerate' quads at each edge of mesh
- Each vertex in the quad has
  - a position
  - a copy of the face normal
  - an extrusion factor of 0 or 1
- For 2 of the quad's vertices
  - The extrusion factor is 0
  - For the other 2, the factor is 1
- If the face normal dot the light direction is zero, extrude the vertex away from the light



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# Volumes on the GPU – Bloating



Original triangle mesh  
6 vertexes  
4 triangles

Bloated triangle mesh  
12 vertexes  
10 triangles

Formula for geometry:

$$V_{\text{bloat}} = 3 * t_{\text{orig}}$$

$$t_{\text{bloat}} = t_{\text{orig}} + 2 * e_{\text{orig}}$$

Bloated geometry based only on number of *triangles* and *edges* of original geometry.

A lot of extra geometry!



# Skinning With GPU Extrusion

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- If performing a non-linear transformation, like skinning, you don't know the face normal
  - Unless you know all 3 of the face vertices' positions
- So, if doing skinning, you must, for each edge of the model
  - Store all 3 vertex positions making up this face
  - Perform skinning on each
  - Then test the face normal, & extrude
- Very expensive for skinned models



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# Good To Be GPU Bound, Right?

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- **Depends: vertex bound, pixel bound, or setup bound?**
- **Current generation hardware: pixel shader horsepower has grown much faster than other two**
- **Setup in particular is still 1-2 clocks per triangle**
  - **Degenerate triangles eat up setup time**
  - **Setup bound → Rendering will scale with clock only**
  - **Clocks haven't gone up quite as much**
- **Future hardware and API could change this picture**

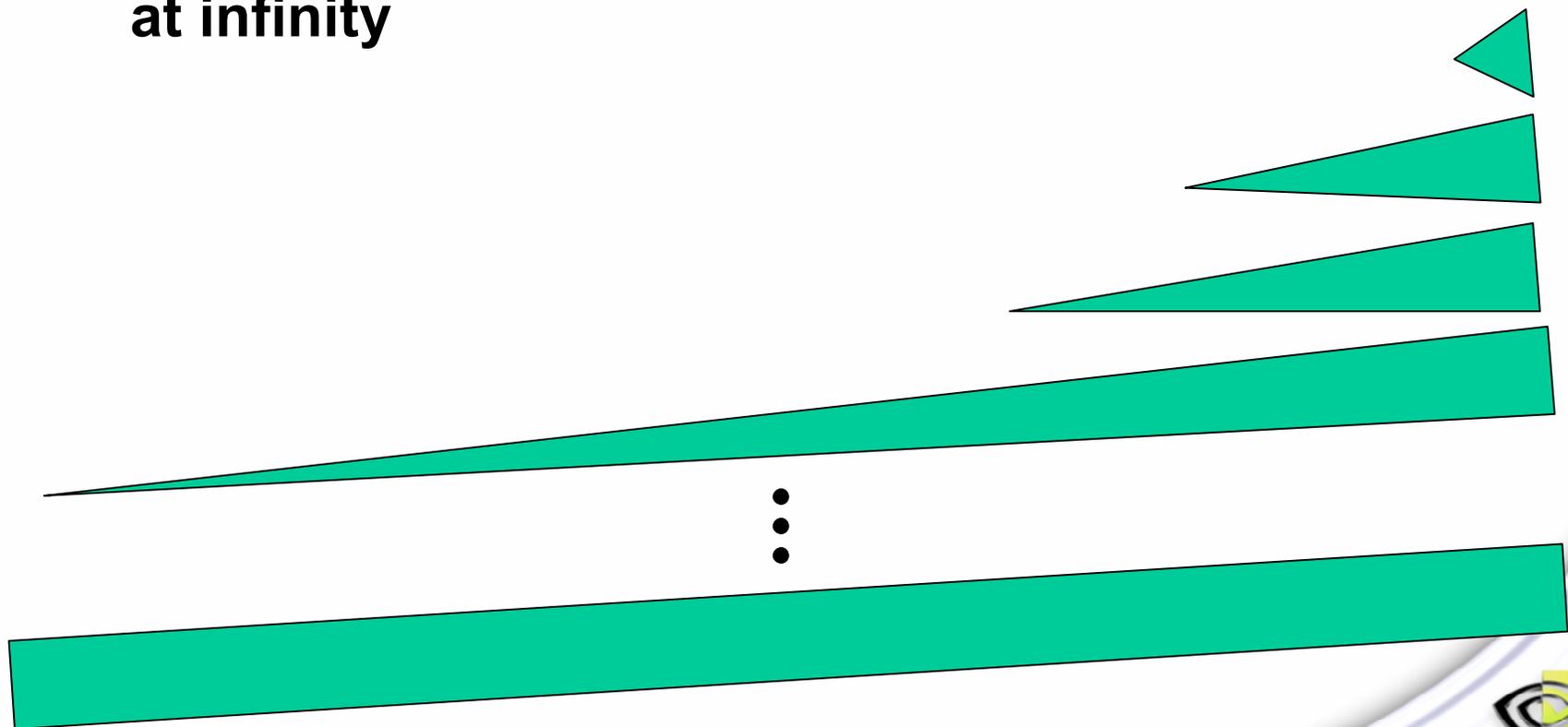


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# Reducing Setup Dependency

- Turn extruded quads into extruded tris
- A quad can be viewed as a triangle with one vertex at infinity





## Quad → Tri

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- **Rather than drawing a quad for each triangle edge, draw a triangle with one vertex having a w coordinate of zero for directional lights**
  - This is known as an external vertex
  - Twice as fast if you are setup bound
  - One triangle instead of two for a quad
  - 25% faster if you are vertex bound
  - Also has more subtle benefits to rasterizer, b/c the quad isn't two skinny triangles, but one long, fat triangle





## Other Optimizations For SSVs

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- **Two-sided Stencil (DX9)**
  - Send both front and back faces at same time
- **Semi-automatic shadow volume extrusion**
  - CPU performs possible silhouette edge detection for each light
  - GPU projects out quads from single set of vertex data based on light position parameter
  - Doom3's approach
- **Depth bounds, depth clamping**
- **See Everitt and Kilgard presentations/papers for all things SSV ([www.developer.nvidia.com](http://www.developer.nvidia.com))**



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# Pros and Cons of SSVs

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- **+ Automatic self-shadowing**
- **+ Omni-directional lights**
- **+ Minimal aliasing and resolution issues**
- **- No area lights, no soft shadows**
- **- Mesh must be 2-manifold (closed) w/ connectivity**
- **- Consumes fill rate**
- **- Need silhouette computation**
  - **Could eat precious CPU cycles**
- **- Not compatible with alpha test**
- **- Inherently multi-pass!**
- **- Popping esp. with low poly counts**



# Pixel Power!

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- **Going forward, pixel shader math horsepower will grow faster than :**
  - **Texture fetching & filtering**
  - **Vertex shader horsepower**
  - **Triangle Setup**
  - **CPU power**
  - **Memory bandwidth**
  - **Just about anything else**



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# Leveraging Pixel Power For Shadows

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- **Shadow Maps**
- **Image-space technique**
  - No knowledge of scene geometry
  - But aliasing...
- **Well-known technique**
  - Ubiquitous in production Renderman shaders
- **Hardware-accelerated since GeForce3**
- **Scales with *pixel* power**



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# Shadow Maps – Basic Algorithm

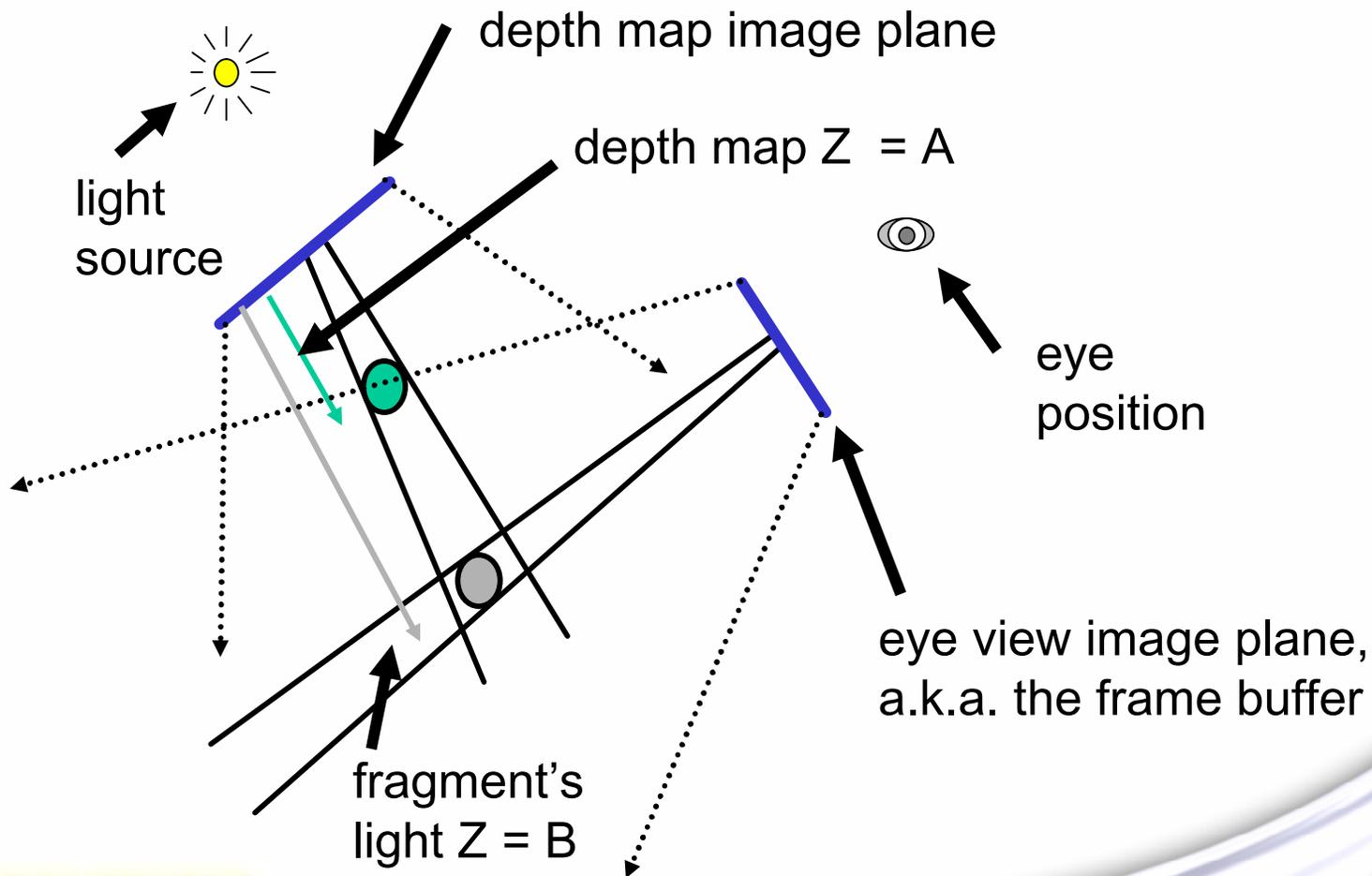
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- Several variations on the same theme
- Light can “see” point  $\Leftrightarrow$  Point is not in shadow
  - Render objects from the light’s POV, storing *depth* from the light into the shadow map
  - Render objects from the camera’s POV, but also test their depth with respect to the light
  - If this object’s depth  $\approx$  the closest object in the shadow map, then object is lit
  - Else object is in shadow

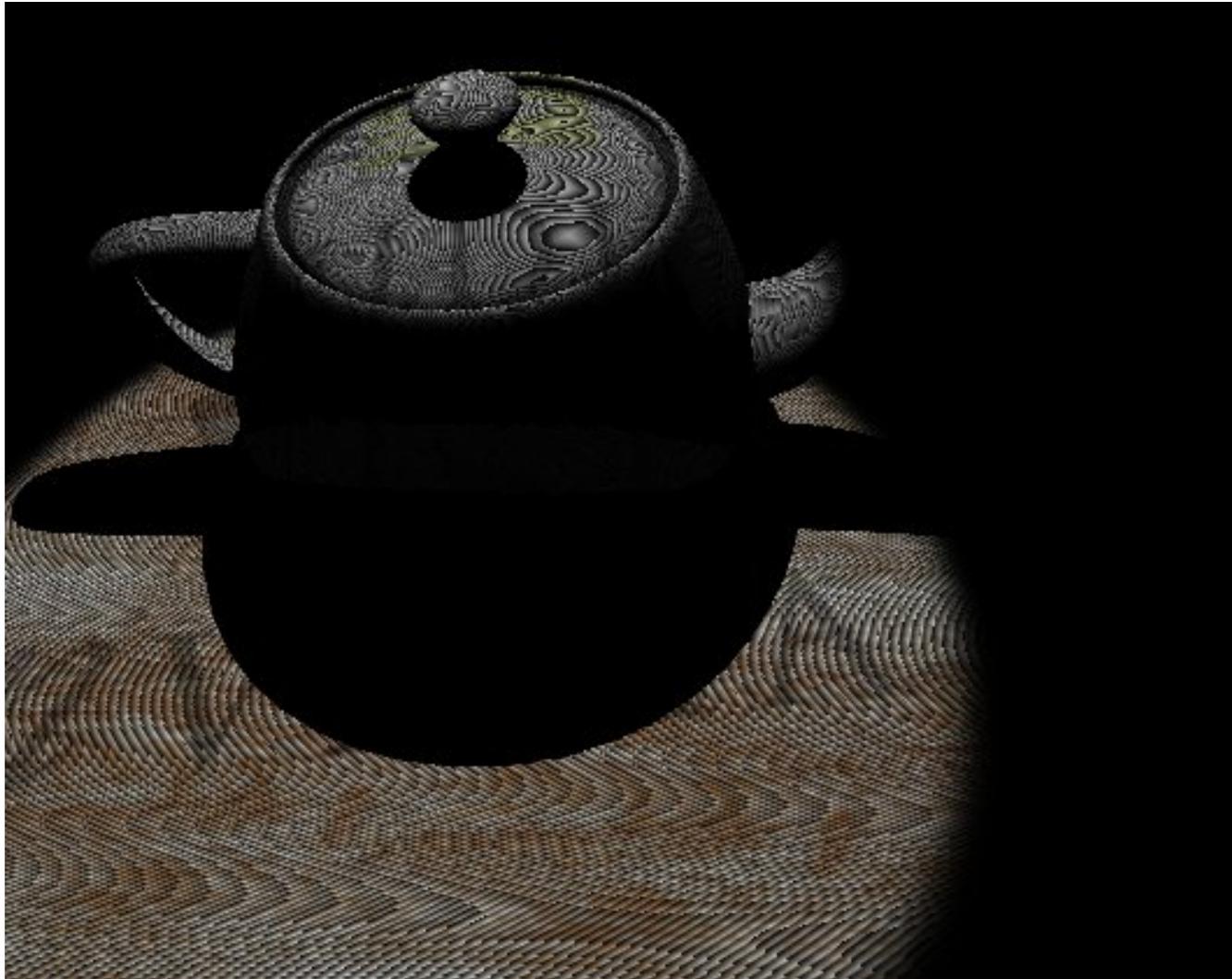


# Shadow Maps – Example

## The $A < B$ shadowed fragment case



# The Result So Far...



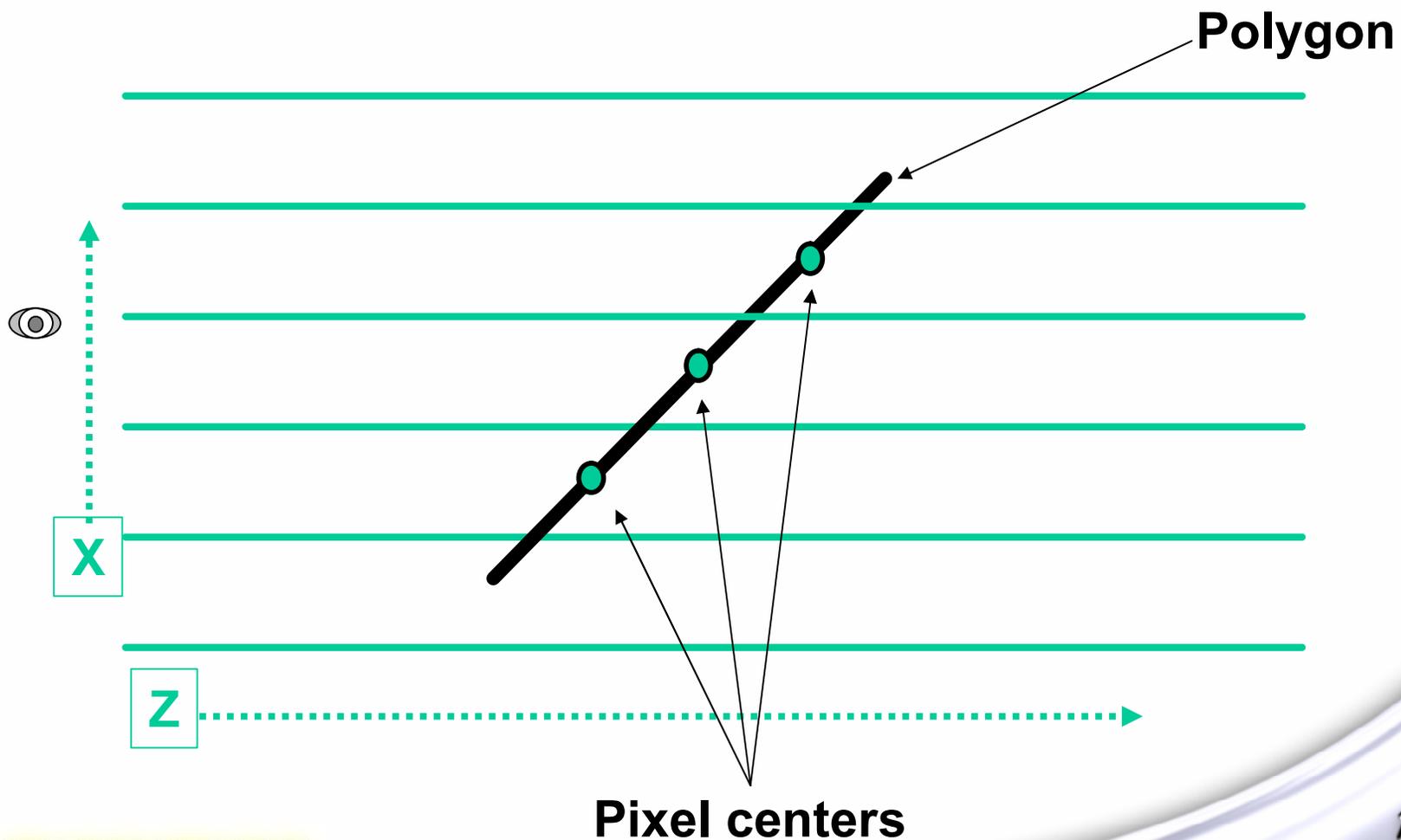
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# What Is Going On?

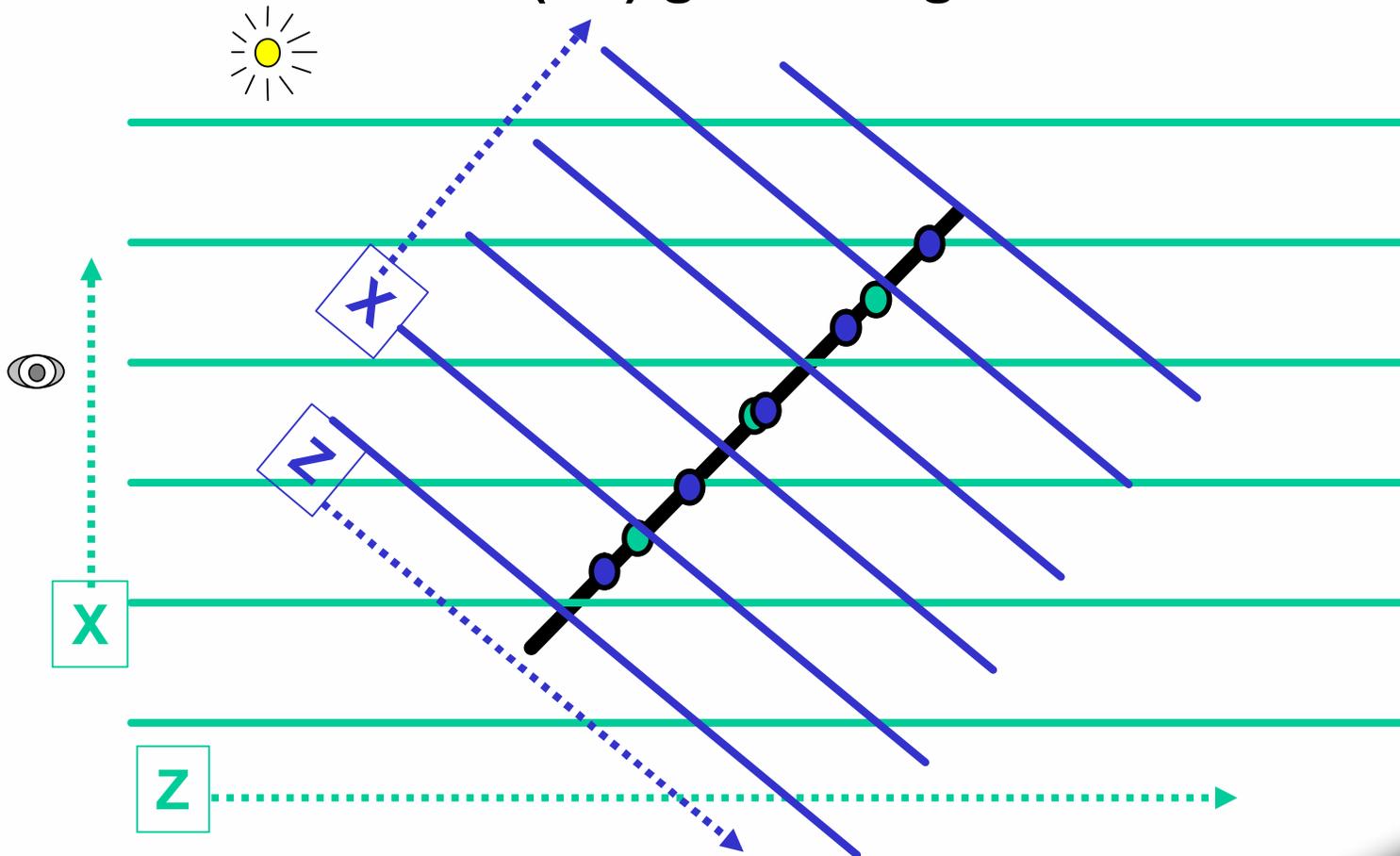
- Consider 2D view of polygon (x and z == depth)





# Depth Aliasing

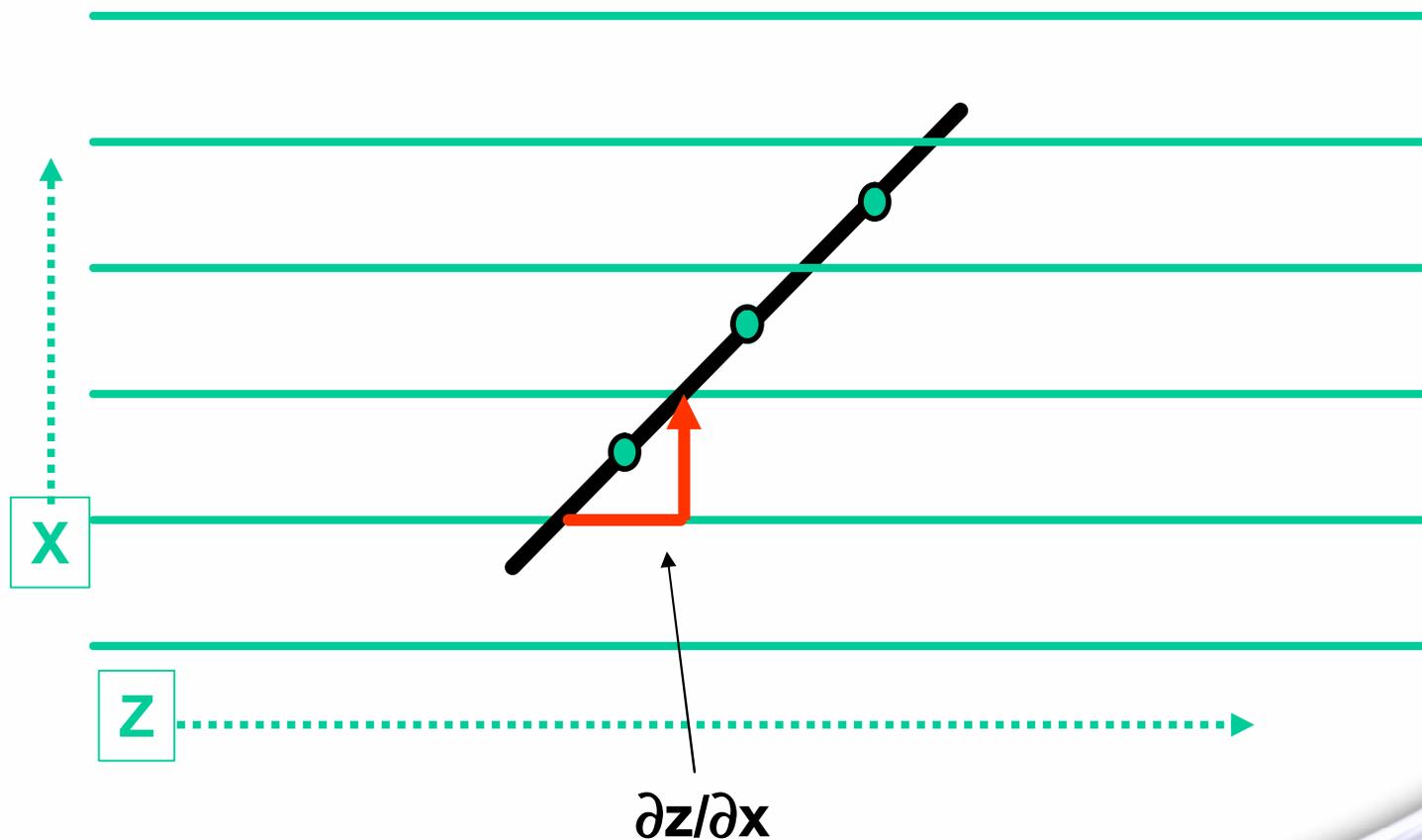
- Add another (2D) grid for light view





# Depth Aliasing – Measuring Error

- Change of Z w.r.t. X





# Depth Aliasing – Maximum Error

- Pixel center is re-sampled to shadow map grid
- The re-sampled depth could be off by  $\pm 0.5 \frac{\partial z}{\partial x}$  and  $\pm 0.5 \frac{\partial z}{\partial y}$
- The maximum absolute error would be  $|0.5 \frac{\partial z}{\partial x}| + |0.5 \frac{\partial z}{\partial y}| \approx \max(|\frac{\partial z}{\partial x}|, |\frac{\partial z}{\partial y}|)$
- Assumes the two grids have pixel footprint area ratios of 1.0
- Otherwise *relative resolutions* of grids will determine scale



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# Simple Bias Will Not Work

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- **Post-perspective divide  $\rightarrow$  depth distribution is non-linear**
- **Need to bias in post-projective space**
- **Need to account for slope of polygon**



# Depth Bias

- DX9:

$$\text{Offset} = m * \text{D3DRS\_SLOPESCALEDEPTHBIAS} + \text{D3DRS\_DEPTHBIAS}$$

- Where  $m = \max(|\partial z/\partial x|, |\partial z/\partial y|)$
- Offset is added *before* the depth test and *before* depth value is written into shadow map
- Exactly what we want!
  - Set *slope scale bias* to adjust for resolution scale
  - Set *depth bias* to adjust for total error
- (OpenGL: *glPolygonOffset* is similar)



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## Are We Done?

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- Unfortunately, not quite
- How to select bias
  - Magnified shadow maps require larger scale
- Problem: *depth precision* (or lack thereof)
  - Use higher precision depth: D16 → D24
  - Not a scalable solution
- Problem: *perspective aliasing*
  - Depth distribution is not uniform
  - Objects distant from light may be close to viewer
  - Shadow texels near camera can be very large
  - Use higher res → again not scalable

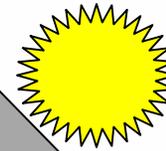


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# Per-Object Shadow Maps

- Instead of measuring depth across the light range in  $(0,1)$

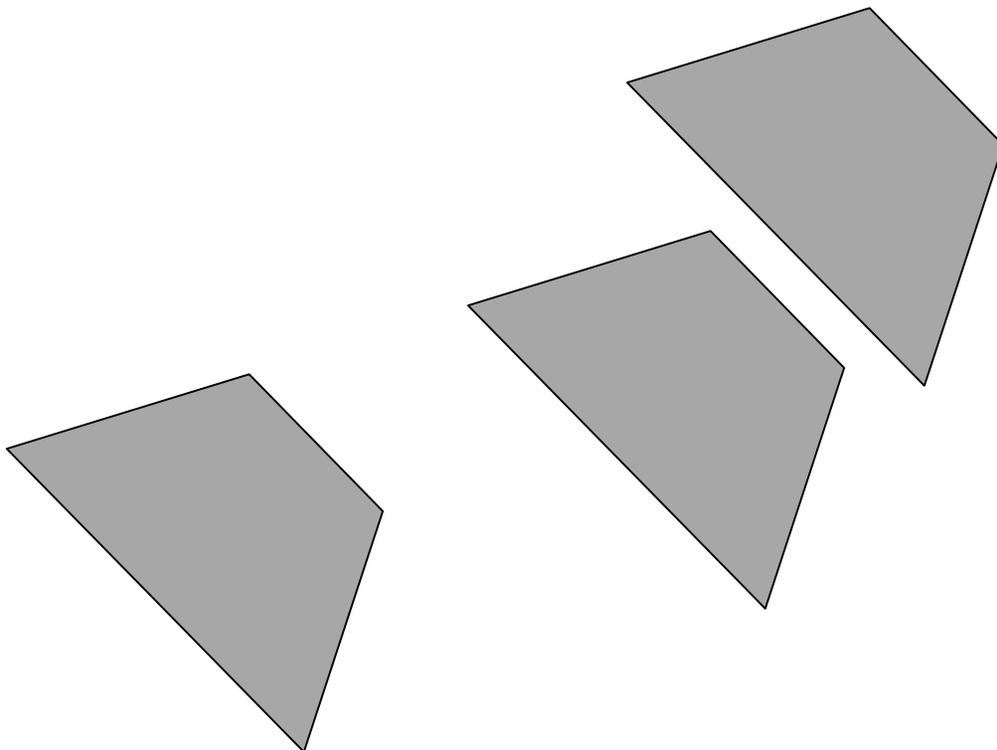
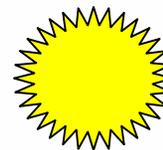


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# Per-Object Shadow Maps

Each object has its own  
depth measured in  $(0,1)$





## Per-Object Maps – Pros and Cons

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- Increased depth precision per object
- Possible reuse per frame
- Can pack multiple shadow maps into ‘shadow map atlas’
  - Saves render target switches
- Could get away with 8 bits of depth
  - Support self-shadowing in ps1.1 hardware
- Only supports local objects, not world geometry
- Too many casters → performance problems
  - Merge close casters into one frustum



# What About Perspective Aliasing?

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- **Shadow texels far from light, close to viewer get magnified**
  - **Fundamental property of projection transform**
- **Sampling is done independent of the view matrix**
  
- **Idea: Transform light space in a *view-dependent* manner**



# Perspective Shadow Maps

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- **Generate the map in *post-projective* space.**
  - Originally proposed by Stamminger/Drettakis, 2002
  - Key Improvements/Elaboration: Kozlov, GPU Gems  
[http://developer.nvidia.com/object/gpu\\_gems\\_home.html](http://developer.nvidia.com/object/gpu_gems_home.html)
- **For a directional light**
  - Take 'LookAt' matrix from post-projective light space to view space
  - Compose with scene  $\text{View} * \text{Projection}$



## PSMs – Pros And Cons

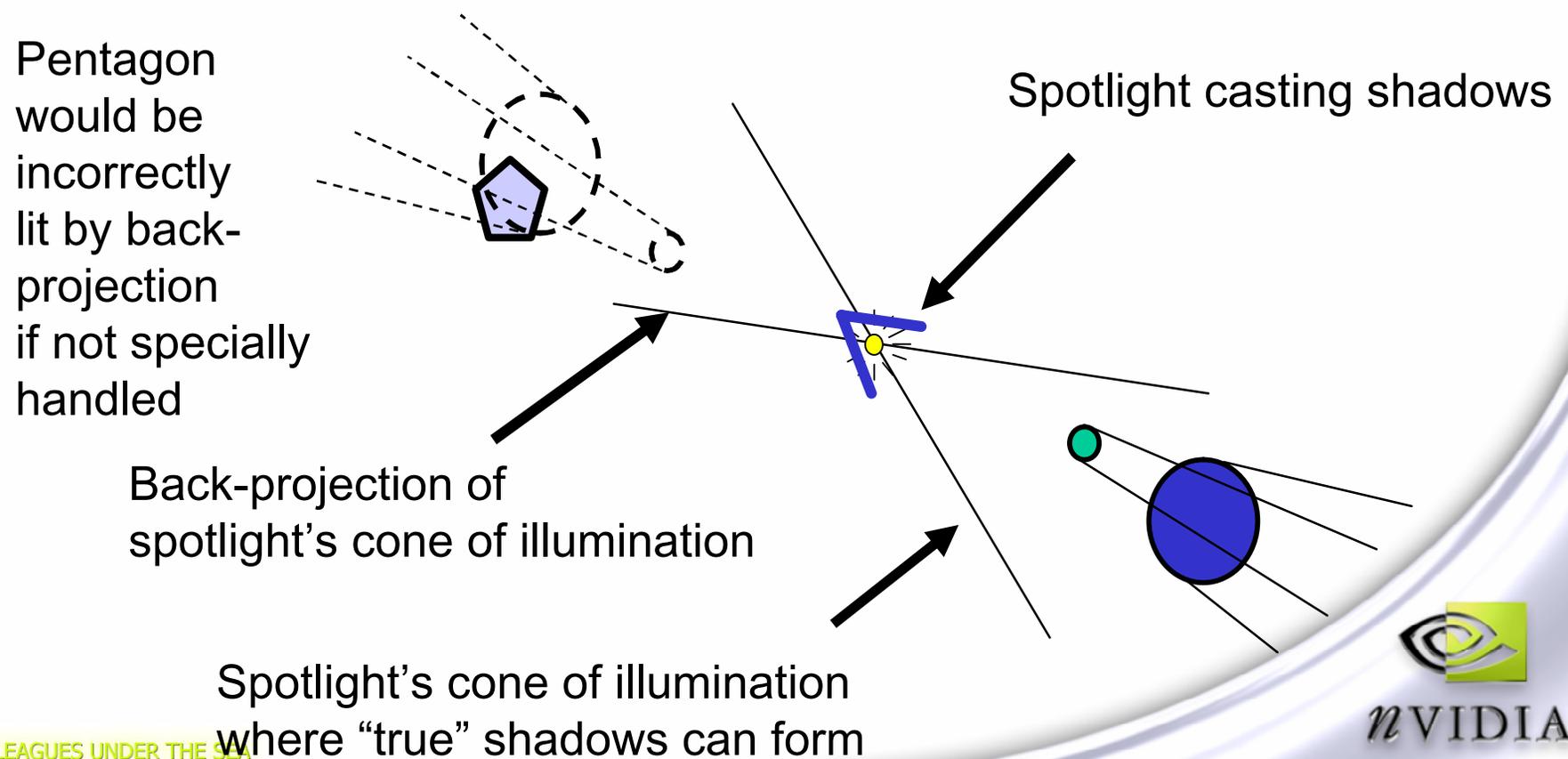
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- **Reduces perspective aliasing significantly**
- **Tricky to implement (and get right)**
  - **See Gary King's NVSDK demo for implementation**
- **CPU-side computations needed for speedups**
- **View dependence → Caching schemes defeated**



# Are We Out Of The Woods Yet?

- **Just like standard projective textures, shadow maps can back-project**





# Eliminating Back Projection

- **Modulate shadow map result with lighting result from a single per-vertex spotlight with proper cut off**
  - **Ensures light is “off” behind the spotlight**
- **Use small 1D texture – s is planar dist from light**
  - **Lookup is 0 for negative distances, 1 for positive**
- **Clip plane positioned at light position OR**
- **Simply avoid drawing geometry behind light when applying shadow map**



## Other Tricks With Shadow Maps

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- Render *back* faces into map instead of front
  - Leakage moved to less noticeable areas
- Shrink shadow casters
  - Minimize self-shadowing artifacts (works with SSVs)
- Omni-directional shadow 'cube' maps (Newhall/King)
  - Simulate cube map with 2D texture
  - Lookup with an auxiliary smaller cube map



# Pros and Cons of Shadow Maps

- **+ Image space → Pixel based**
  - Independent of vertex programs – skinning
  - Independent of scene complexity
- **+ No special requirements for geometry**
  - No CPU side computations (in general)
- **+ Soft shadows, filtering**
- **+ Works great with multi-pass**
  - Can collapse multiple lights using SM3.0
  - Compatible with alpha test
- **- Omni-directional lights?**
- **- Resource consumption (textures, render target switching)**
- **- Aliasing issues**



# World v. Local Geometry

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- **Probably best to mix and match techniques**
- **World Geometry**
  - Light maps
  - Stencil Shadow Volumes
  - Precomputed Radiance Transfer
  - Projective Shadow Maps
- **Local Geometry a.k.a. 'objects'**
  - Shadow Maps
  - Per-object Shadow Maps
  - Object ID Shadow Maps



# Hardware Shadow Maps – Use Them!

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- There is no reason not to
- Supported since GeForce3
  - Except GeForce4 MX
- Free Percentage Closest Filtering
  - Weighted average of shadow map comparisons
  - Can combine with higher quality filters
  - Combine with branching in SM3.0 for selective filtering
- Huge perf win v. emulating in shader
- Double speed rendering on GeForce FX and above



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## Credits and References

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- **Cass Everitt, Mark Kilgard. Series of presentations and papers on stencil shadow volumes available from [developer.nvidia.com](http://developer.nvidia.com)**
- **Sim Dietrich (whose original presentation and ideas I stole)**
- **Cem Cebenoyan, Gary King (for valuable insights, and posing deep imponderable questions)**
- **All errors are theirs 😊**
- **But you can complain to me at: [arege@nvidia.com](mailto:arege@nvidia.com)**



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